



STATIC BALANCING

$$\mathbf{F}_S = m_1\omega^2 \mathbf{r}_1 + m_2\omega^2 \mathbf{r}_2 + m_3\omega^2 \mathbf{r}_3$$

$$m_1\omega^2 \mathbf{r}_1 + m_2\omega^2 \mathbf{r}_2 + m_3\omega^2 \mathbf{r}_3 + m_c\omega^2 \mathbf{r}_c = \mathbf{0}$$

$$m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2 + m_3 \mathbf{r}_3 + m_c \mathbf{r}_c = \mathbf{0}$$

$$\sum_{n=1}^N m_n \mathbf{r}_n + m_c \mathbf{r}_c = \mathbf{0}$$

$$m_1 r_1 \cos\theta_1 + m_2 r_2 \cos\theta_2 + m_3 r_3 \cos\theta_3 + m_c r_c \cos\theta_c = 0$$

$$m_1 r_1 \sin\theta_1 + m_2 r_2 \sin\theta_2 + m_3 r_3 \sin\theta_3 + m_c r_c \sin\theta_c = 0$$

$$m_c r_c = [(m_1 r_1 \cos\theta_1 + m_2 r_2 \cos\theta_2 + m_3 r_3 \cos\theta_3)^2 + (m_1 r_1 \sin\theta_1 + m_2 r_2 \sin\theta_2 + m_3 r_3 \sin\theta_3)^2]^{1/2}$$

$$\theta_c = \arctan [(-m_1 r_1 \sin\theta_1 - m_2 r_2 \sin\theta_2 - m_3 r_3 \sin\theta_3) / (-m_1 r_1 \cos\theta_1 - m_2 r_2 \cos\theta_2 - m_3 r_3 \cos\theta_3)]$$



Static Balancing

Dinamika Mesin

Fredy S., S. T.

